



Self-Interference Cancellation Towards Real-Time Spectrum Sensing in Vehicular Dynamic Spectrum Access Systems

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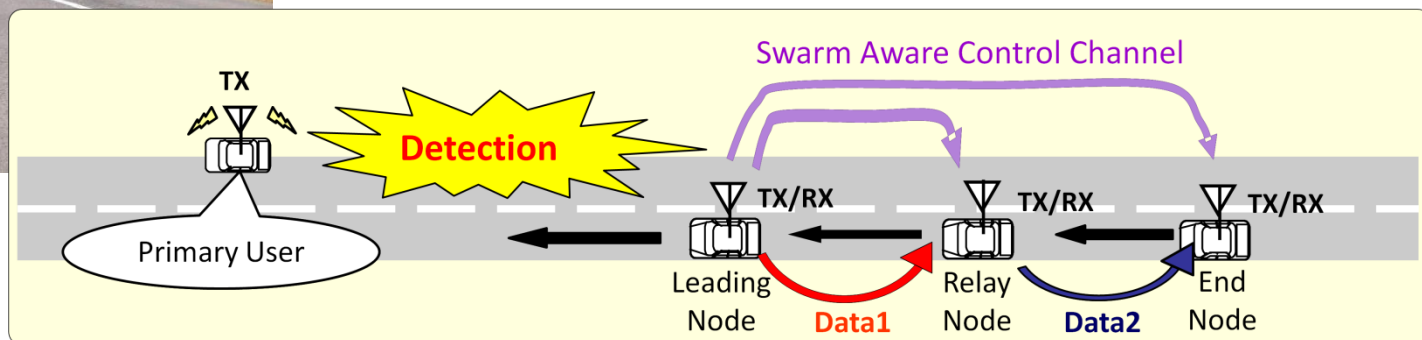
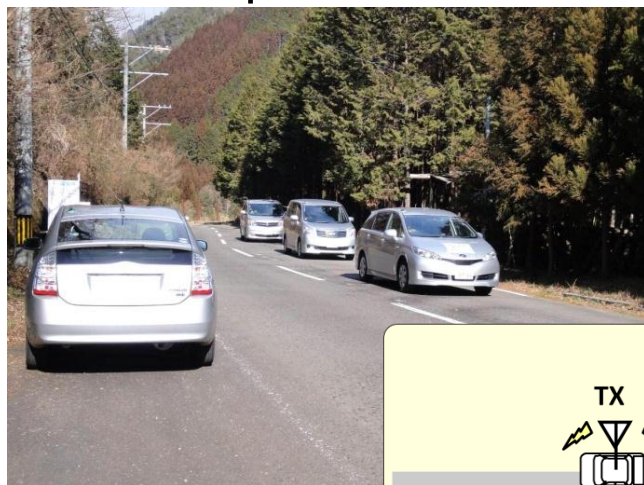
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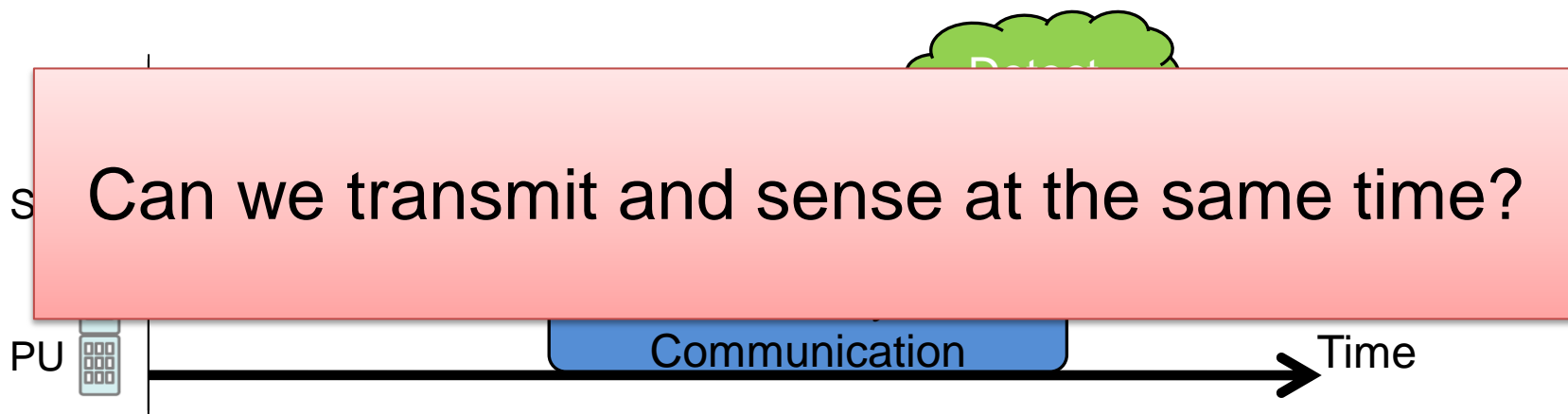
- ◆ Motivation
- ◆ Sensing with self-interference cancellation
 - Cancellation in analog domain
 - Cancellation in digital domain
- ◆ Performance evaluation
 - Experimental setup
 - Results
- ◆ Conclusion

◆ Dynamic spectrum access (DSA) in the vehicular environment

- We developed proof of concept demo
- Ad-hoc vehicular network in TV white space
 - [Altintas et al, Mobicom '12], [Ihara et al, CCNC '13]
- Spectrum awareness is achieved through sensing



- ◆ Alternate between sensing and communication intervals
- ◆ Drawbacks of quiet periods:
 - Lower channel utilization
 - Possible delay in detection of PUs
 - ✓ In the vehicular environment spectrum occupancy changes faster
 - Mobility creates difficulties in time synchronization of sensors
 - ✓ GPS signal can be lost
 - ✓ Connectivity between nodes can be lost



- ◆ Full duplex wireless communication [Choi et al '10]
 - Cancel self-interference to transmit and receive at the same time
 - We use similar approach for different purpose

- ◆ Detecting a PU by observing interference it creates to SUs [Boyd et al '12]
 - The same purpose but different approach

- ◆ Self-interference cancellation using MIMO [Hua et al '12]
 - Use beamforming to achieve full duplex communication
 - Assumes the channel between Tx and Rx (sensor) is known

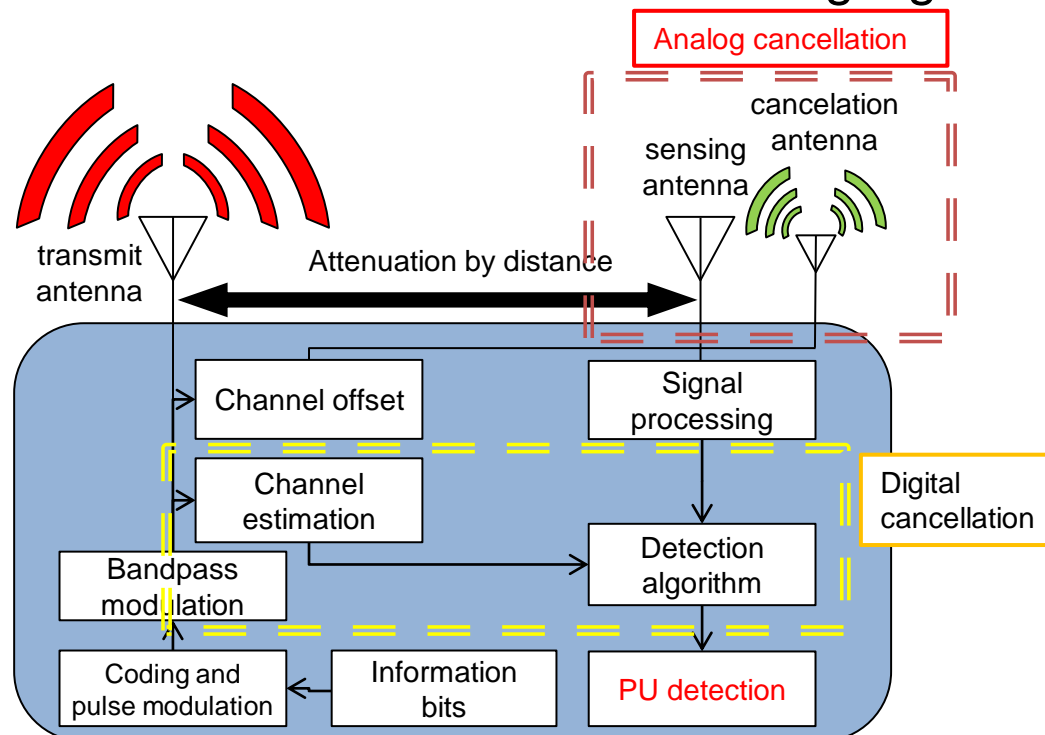
Two stage self-interference cancellation

◆ Analog domain

- Separate antenna injects opposite phase SU Tx signal into sensor

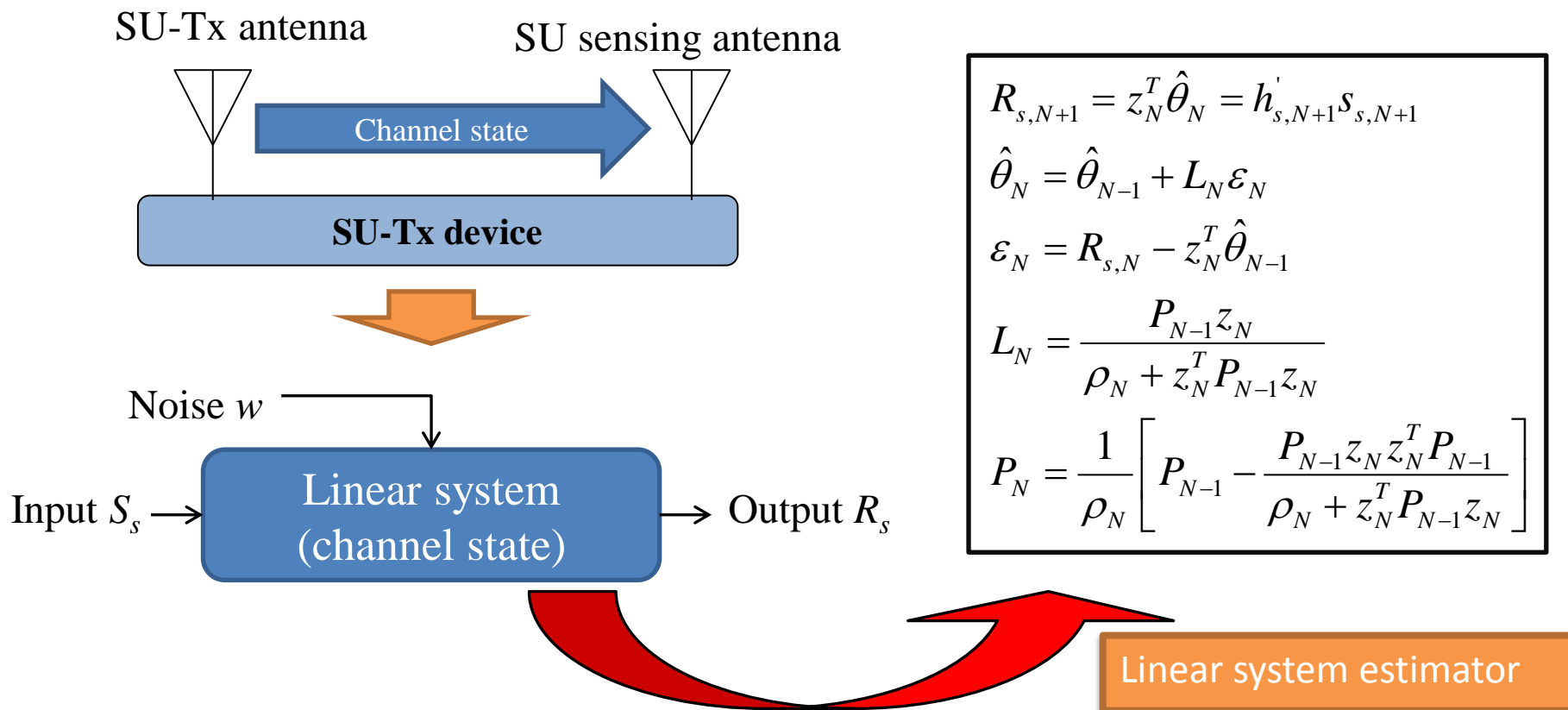
◆ Digital domain

- Subtraction of self-interference from sensing signal



- ◆ Preconditions the signal for digital cancellation
 - Prevents DAC saturation due to strong SU Tx signal
 - Reduces dynamic range of the sensing signal
 - ✓ Reduces DAC quantization error of weak PU signal in presence of strong SU signal
- ◆ Vehicles present favorable platforms for antenna cancellation
 - Some SU attenuation is achieved through distance between the Tx and the sensing antenna on the car roof
- ◆ Cancellation antenna is much closer to sensing antenna
 - Low cancellation power affects SU signal only in the proximity of the sensing antenna

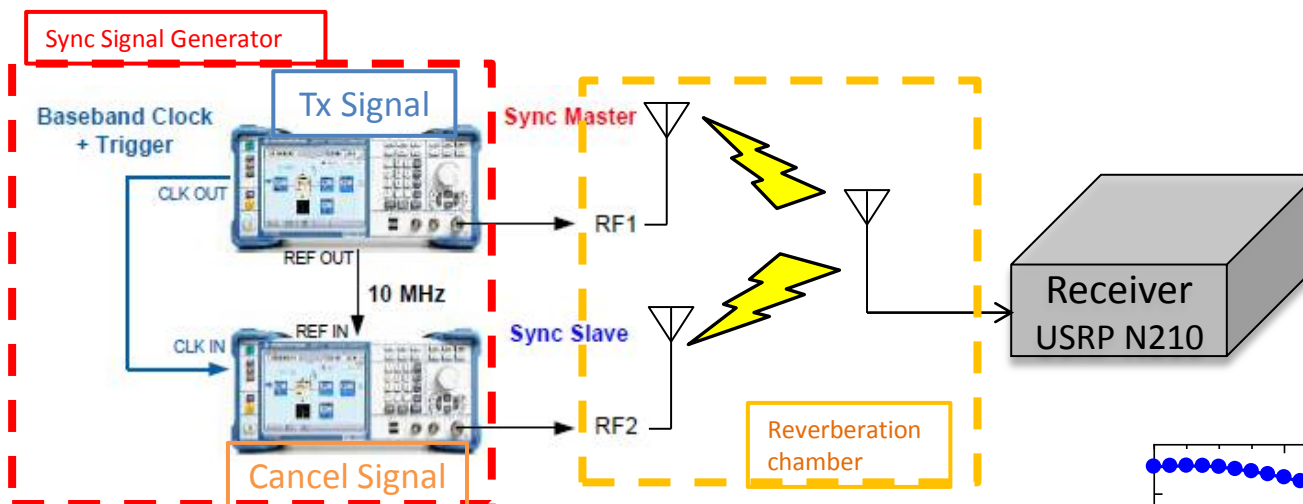
- ◆ Subtract Tx signal replica from the output of analog cancellation
 - Includes RLS MMSE estimation of the channel between the Tx and sensing antennas



- ◆ Analog domain cancellation is evaluated experimentally
 - In controlled laboratory conditions
 - ✓ With sophisticated signal generators
 - ✓ In a reverberation chamber
 - ✓ Achieved **25 dB** reduction
 - Outdoors
 - ✓ On a stationary vehicle
 - ✓ Using Ettus USRP N210
 - ✓ Achieved **20 dB** reduction

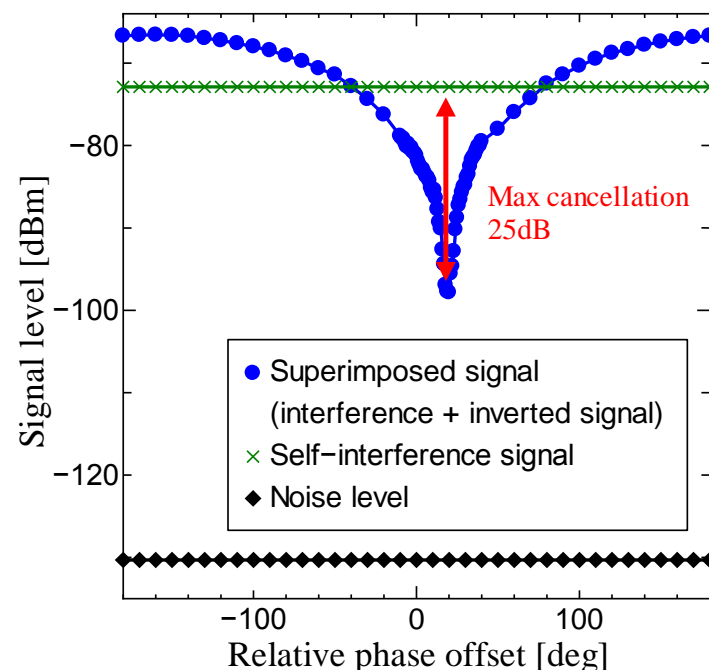
- ◆ Digital domain cancellation is evaluated numerically
 - Achieved **40 dB** reduction

Analog cancellation in lab environment

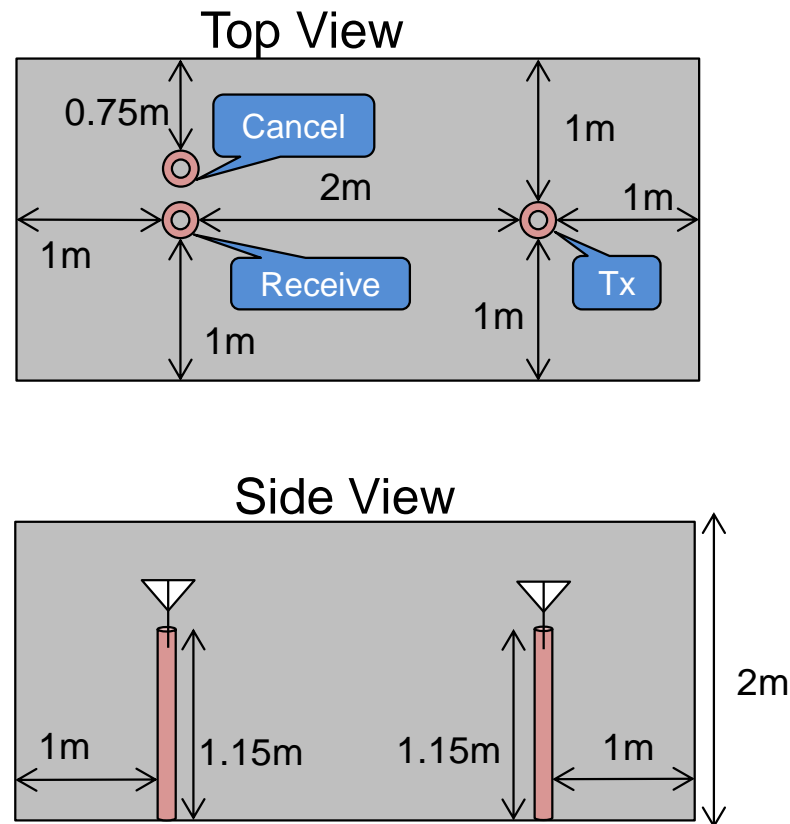
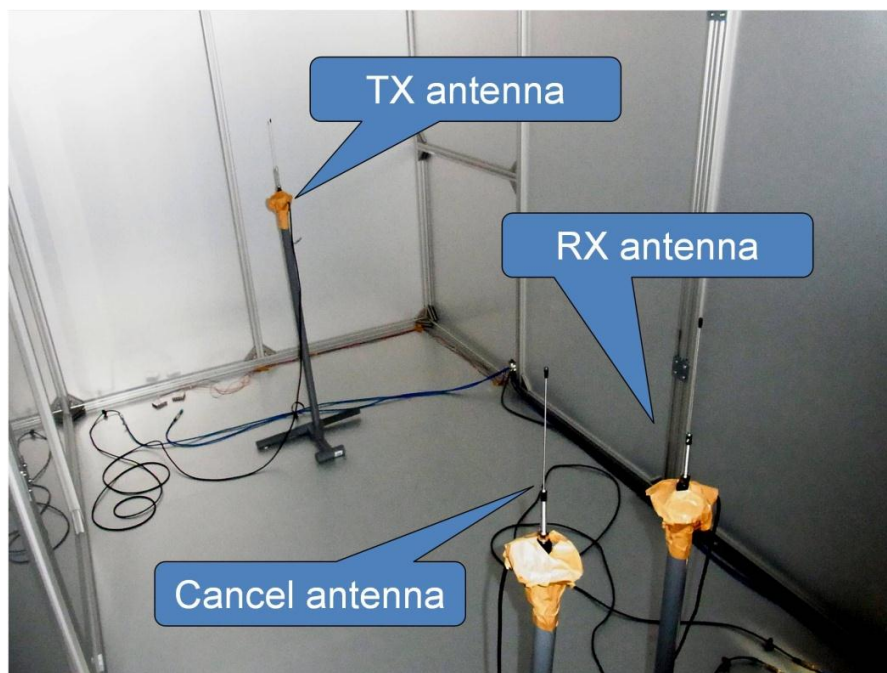


We adjust **phase offset** of the cancelation signal in **baseband** to achieve maximum suppression.

Result

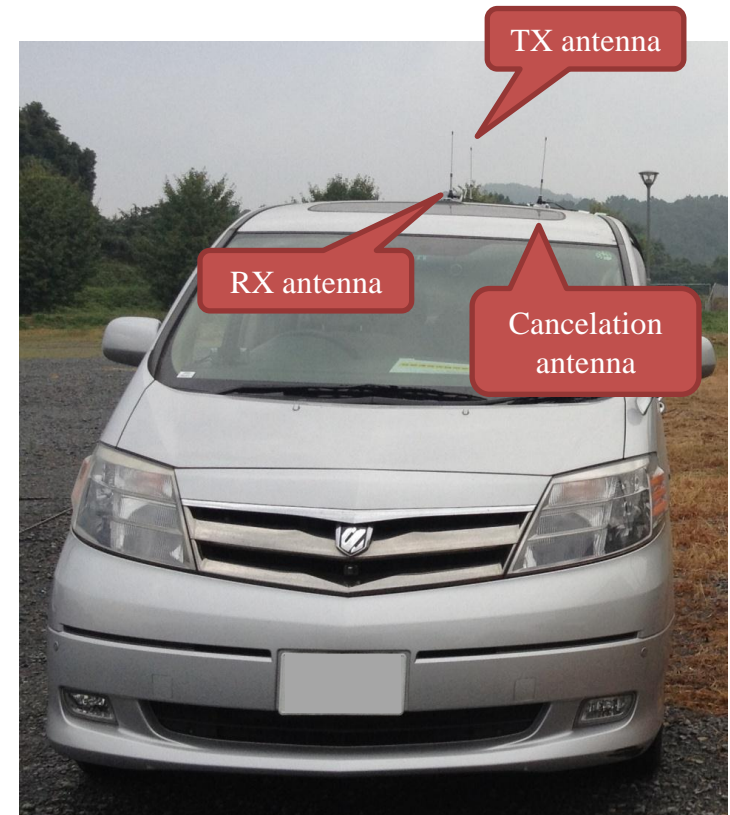
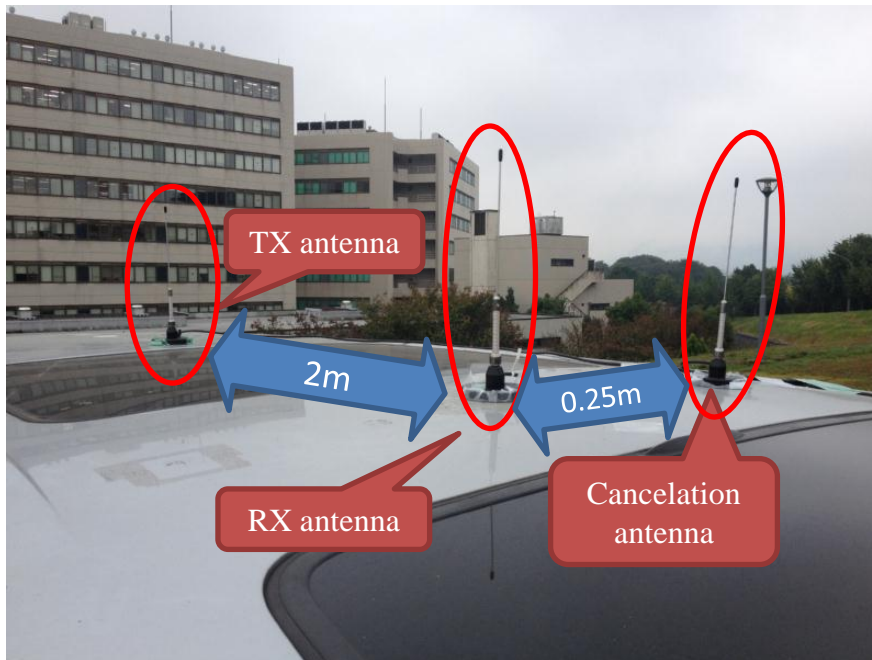


- ◆ Enables experimenting in the licensed TV band
- ◆ Provides rich multipath Rayleigh-like environment
 - Testing under unfavorable conditions



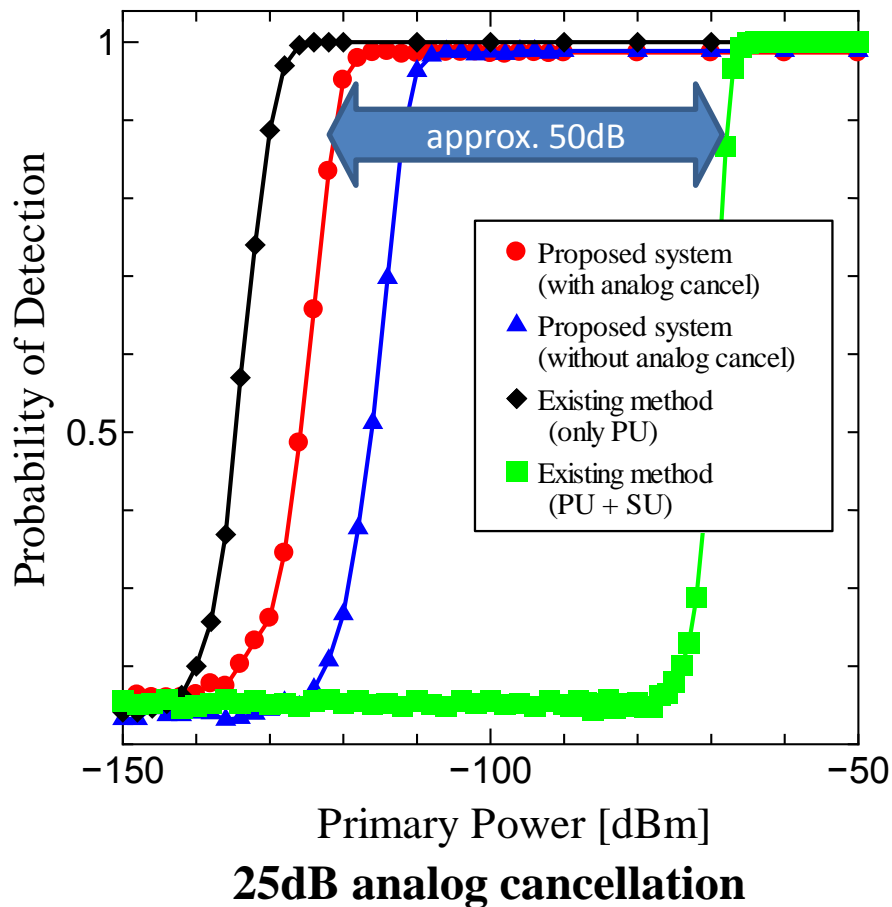
Analog cancellation outdoors

- ◆ With an experimental license valid in Iizuka, Kyushu
- ◆ Using synchronized USRP N210 radios

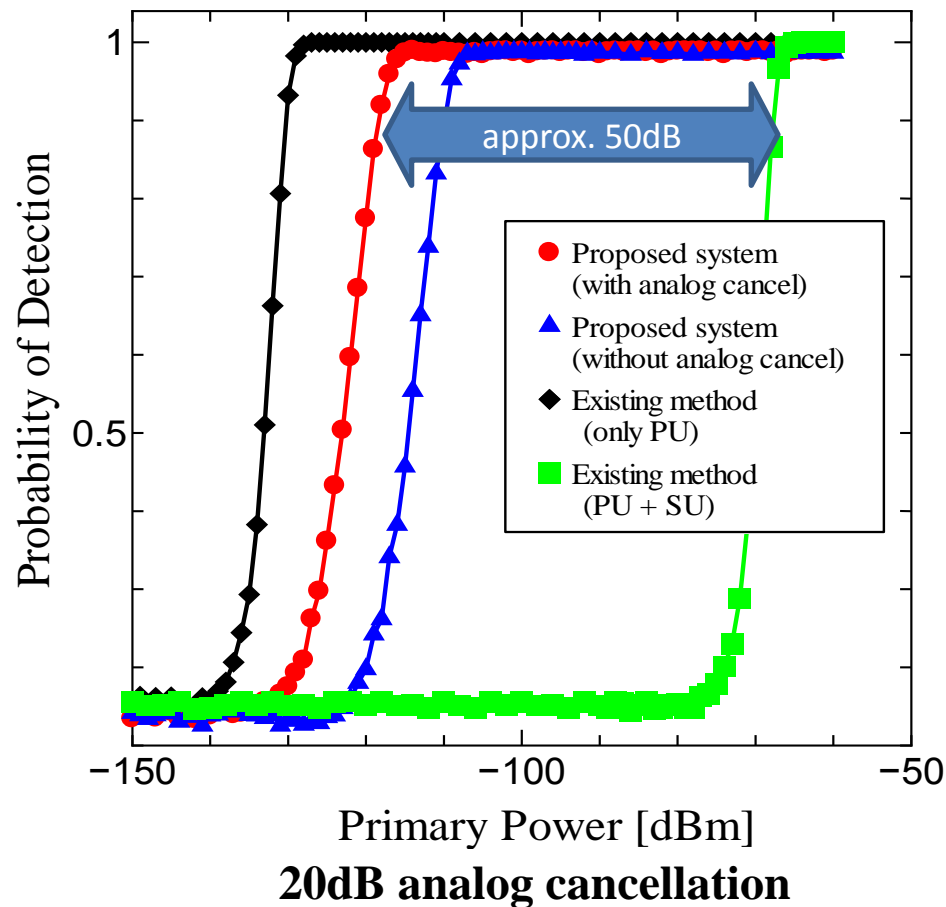


Energy Detection Threshold is set to satisfy
probability of false alarm $P_{FA} = 0.15$

Self-interference receive power : -70dBm



Self-interference receive power : -70dBm



- ◆ We presented and evaluated first step towards simultaneous sensing and transmitting in the vehicular environment
- ◆ Two-stage SU self-interference cancellation
 - Analog domain cancellation achieves 20 to 25 dB rejection
 - Digital domain cancellation achieves 40 dB rejection
- ◆ Results:
 - Around 50 dB improvement in detection performance
 - Around 10 dB penalty in detection performance in comparison to sensing during quiet periods

- ◆ Parameter settings for analog cancellation in the lab
- ◆ Parameter settings for digital cancellation
- ◆ Example of RLS-MMSE cancellation
- ◆ Detailed system block diagram

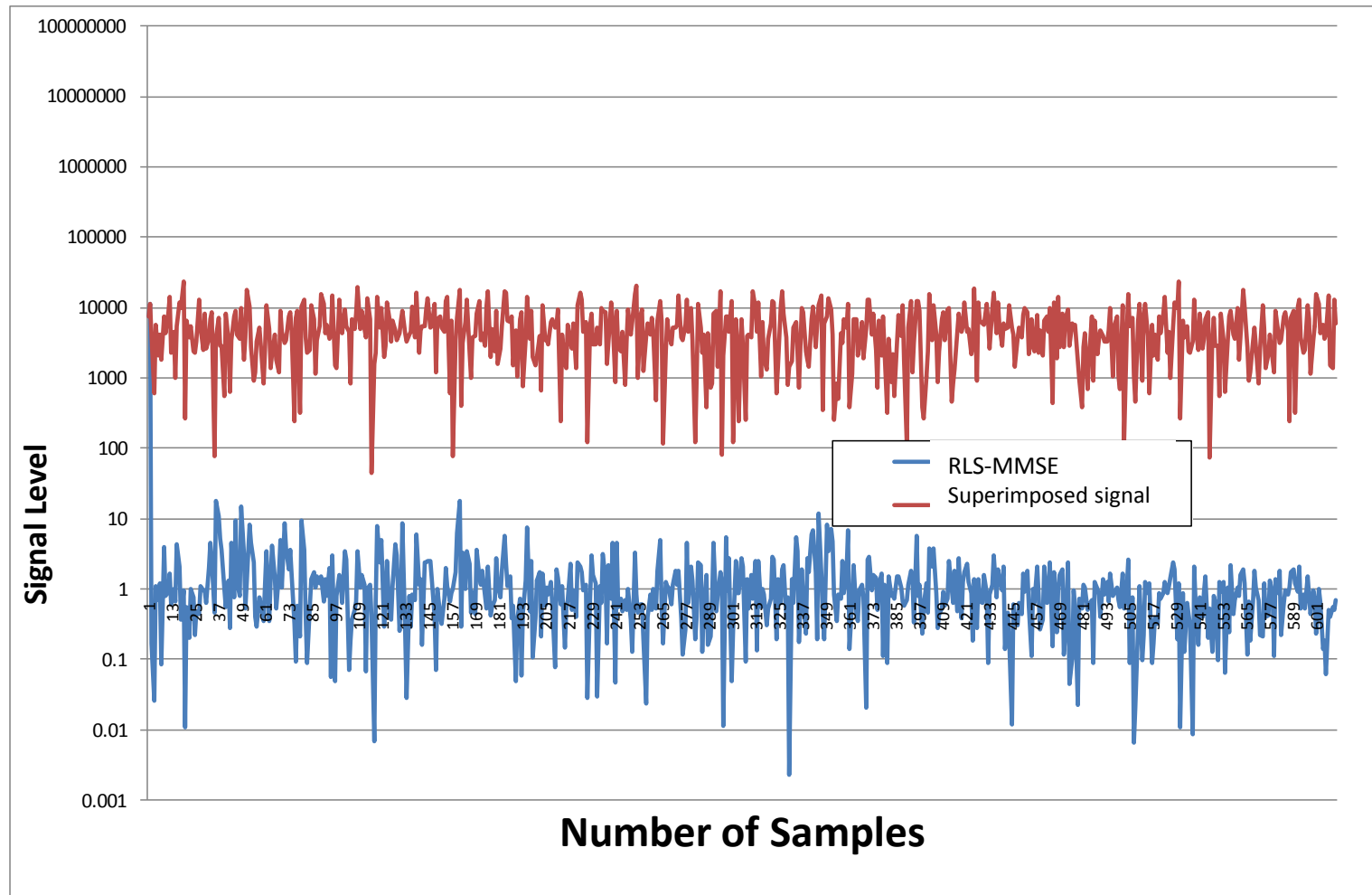
TABLE 1 Experimental Evaluation Parameters

Parameter	Value
Sequence Length	10000 symbols
Data Source	PRBS, PRBS 9
Symbol Rate	100.0 ksym/s
Filter type	Gaussian
Filter coefficient	0.30
Number of samples	320000
Sample Rate	3.20 MHz

TABLE 2 Computer Simulation Parameters

Parameter	Value
Modulation	OFDM,QPSK
Number of symbols at OFDM	10
Number of pilot symbols at OFDM	2
Number of FFT points (per symbol)	512
Number of guard intervals	100
Fading environment	Rayleigh fading
Number of channel taps	8
Number of trials	5000

◆ Secondary SNR 40 dB



Detailed system block diagram

